



2015 Canadian Grand Prix – Stat Sheet

Circuit Gilles Villeneuve, Montreal, 05/06/07 June 2015

Circuit Characteristics

Circuit Length	4.361 km
Race Laps	70
Race Distance	305.270 km
Lap Record	1:13.622
Record Holder	BAR (2002)
Distance from Pole to Turn One Apex	260 m
Pit Lane Length Under Speed Limit Control	417 m
Pit Lane Time at 80 km/h	17.0 s
Number of Corners	14 (6 L/8 R)
Highest Lateral G	3.4 (T5)
% of Lap / Lap Distance at Full Throttle	45% / 59%
Fuel Consumption (1 = Low / 3 = High)	3
Braking Events	6 (4 Heavy)
Brake Energy	High
Track Evolution (P1 – Qualifying)	Low
Tyre Compounds	SS / S
DRS Zones	T 12-13/14-1
Key Overtaking Opportunities	T 13

Race Characteristics (2005 – 2014)*

Races Featuring Safety Car	5 (Last: 2014)
Total Safety Car Deployments	13
Historical Safety Car Probability / Ratio	56% / 144%
Winners from Pole Position	4
Lowest Winning Grid Position	P7 (2005/2011)
Climate	Variable
Historical Weekend Temperature Range	13–34°C
Rain Affected Sessions	7
Rain Affected Races	1
Historical Wet Race Probability	11%

Timetable

Session	EDT (Local Time)	UTC (+4 Hours)
Practice 1	10:00 – 11:30	14:00 – 15:30
Practice 2	14:00 – 15:30	18:00 – 19:30
Practice 3	10:00 – 11:00	14:00 – 15:00
Qualifying	13:00 – 14:00	17:00 – 18:00
Race	14:00	18:00

*No Canadian Grand Prix Held in 2009

2014 Statistics

Fastest Lap P1	1:17.238 (ALO)
Fastest Lap P2	1:16.118 (HAM)
Fastest Lap P3	1:15.610 (HAM)
Fastest Lap Q1	1:15.750 (HAM)
Fastest Lap Q2	1:15.054 (HAM)
Fastest Lap Q3	1:14.874 (ROS)
Delta P1 to Q3	2.364
Delta Q1 to Q3	0.876
Fastest Race Lap	1:18.504 (MAS)
Winning Race Time	1:39'12.830
Winning Average Speed	184.613 km/h
Race Speed Trap	347.1 km/h (MAS)
Podium	RIC/ROS/VET
Winning Strategy	2 Stops (L 13, 37)
Total Race Pit Stops	33
Total Normal Overtakes	4
Total DRS Overtakes	20
Not Classified	6 (5 Mechanical)

107% Sample Times

1:14.000	1:19.180
1:14.500	1:19.715
1:15.000	1:20.250
1:15.500	1:20.785
1:16.000	1:21.320
1:16.500	1:21.855
1:17.000	1:22.390
1:17.500	1:22.925
1:18.000	1:23.460
1:18.500	1:23.995

